

### Related topics

Induction, magnetic flux, coil, magnetic field strength, magnetic field of coils, remanence, coercive field strength

### Principle and task

A magnetic field is generated in a ring-shaped iron core by a continuous adjustable direct current applied to two coils. The field strength  $H$  and the flux density  $B$  are measured and the hysteresis recorded.

### Equipment

Coil, 600 turns	06514.01	2
Iron core, U-shaped, solid	06491.00	1
Iron core, solid	06490.00	1
Iron core, U-shaped, laminated	06501.00	1
Iron core, short, laminated	06500.00	1
Commutator switch	06034.03	1
Power supply, univ., anal. disp.	13501.93	1
Rheostat, 10 Ohm, 5.7 A	06110.02	1
Teslameter, digital	13610.93	1
Hall probe, tangent., prot. cap	13610.02	1
Barrel base -PASS-	02006.55	1
Right angle clamp -PASS-	02040.55	1
Support rod, l 150 mm	02020.15	1
COBRA-interface 2	12100.93	1
PC COBRA data cable RS232, 2 m	12100.01	1
Software COBRA, electric values,	14293.61	1
Basic Softw. f. PHYWE Windows prog.	14099.61	1
Connecting cord, 750 mm, red	07362.01	5
Connecting cord, 750 mm, blue	07362.04	5

### Problems

Record the hysteresis curve for a massive iron core and for a laminated one.

### Set-up and procedure

The experimental set-up is shown in Fig. 1. Connect the computer, the COBRA interface and the Teslameter to a common electric mains power supply. Connect the variable transformer to an electric socket which is as far as possible from the above-mentioned one and, if possible, which uses another phase. In addition, position the coil set-up far from the computer and from the COBRA device to avoid errors during the transfer of data due to interference by the strong magnetic fields. Connect the voltage  $U$  which is measured across the resistor to the analogue input 3 of COBRA and the recorder output port of the Teslameter to the analogue input port 4. Attach the Hall probe under the yoke in such a manner that the sensor is located directly adjacent to the borehole for the positioning pin. The magnetic field of the coils should be reversed with the commutator switch only at a voltage of 0 V as otherwise voltage spikes are generated which can affect data transfer.

### Execution

- Load and start the "Disp\_COM1" or "Disp\_Com2" program
- Select the  $\langle xy \rangle$  mode
- Range settings: "U3/V"  $\rightarrow$   $\langle 100 \rangle$   
"U4/V"  $\rightarrow$   $\langle 1 \rangle$

Fig. 1: Experimental set-up for recording the hysteresis.



- $\langle \Delta t/s \rangle$ : 0.50  
This is the sampling rate for a 486-PC. A Pentium PC can operate at a higher rate e.g. 0.2...0.3 sec.
- Press the second button from the left hand side on top of the diagramme.  
Y axis settings: Maximum: 1.000  
Minimum: -1.000  
Units/division: 0.100
- Press the fourth button from the left hand side on top of the diagramme.  
X axis settings: Maximum: 15.000  
Minimum: -15.000  
Units/division: 2.000
- Set the rheostat to 10  $\Omega$ .
- Set the measuring range on the Teslometer to 2000 mT.
- Set the Teslometer to Direct Field and adjust the zero point in air using the rotary type switch above the probe jack.
- If residual magnetism is present in the iron core, demagnetise the core as follows:  
  
Set the commutator switch in such a manner that an opposing field is generated. Briefly increase the voltage far enough for the flux density to assume a zero value; repeat a number of times.
- Set current limiter on the power supply to 5 A.
- After pressing the  $\langle \text{Start} \rangle$  button, start the measurement procedure by clicking the  $\langle \text{Reset} \rangle$  key.
- Increase the voltage slowly and uniformly from zero upwards and decrease it to zero again.
- Using the commutator switch reverse the polarity of the voltage.
- Again increase and then decrease the voltage slowly and uniformly.
- Once again reverse the polarity of the voltage with the commutator switch and increase the voltage.

- Stop the measurement procedure and press the  $\langle \text{Stop} \rangle$  button.
- Reset the voltage to 0 V.

**Theory and evaluation**

Since the COBRA interface can only measure voltages, the current measurement is performed with the aid of a 10  $\Omega$  rheostat.

$$I = U/10\Omega \quad (1)$$

Furthermore, the field strength is calculated with the formula

$$H = I \cdot n/L$$

where  $H$  = field strength

$n$  = number of turns in the coil (600 turns)

$L$  = average field line length in the core.

(solid core:  $L = 232$  mm

laminated core:  $L = 244$  mm)

The following correlation between the field strength and the measured voltage results:

$$H = (n/ (L \cdot 10\Omega)) \cdot U$$

The factor  $n/ (L \cdot 10\Omega)$  changes due to the different dimensions of the two iron cores as follows:

Solid iron core:  $(n/ (L \cdot 10\Omega)) = 258.62$  in  $1/(m \cdot \Omega)$

Laminated iron core:  $(n/ (L \cdot 10\Omega)) = 245.90$  in  $1/(m \cdot \Omega)$

A comparison of Figs. 2 and 3 shows that the remanence and coercive field strength are substantially greater in a solid iron core than in a laminated one.

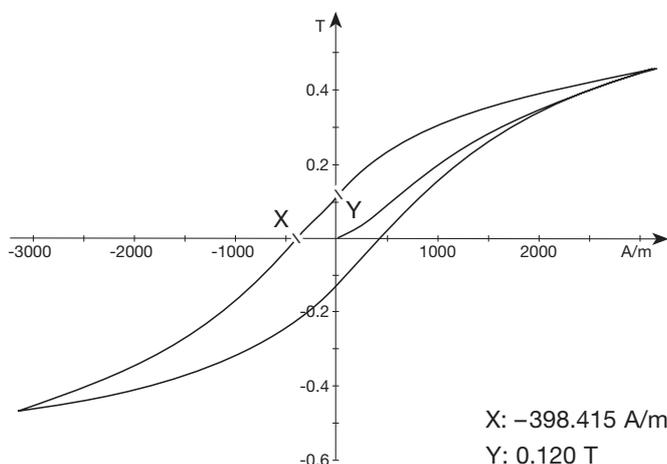


Fig. 2: Hysteresis for a solid iron core;  
 $|X|$  = coercive field strength; Y = remanence

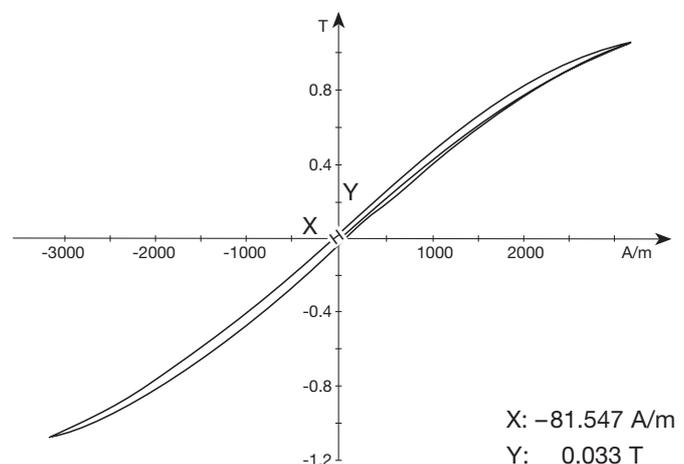


Fig. 3: Hysteresis for a laminated iron core;  
 $X$  = coercive field strength; Y = remanence