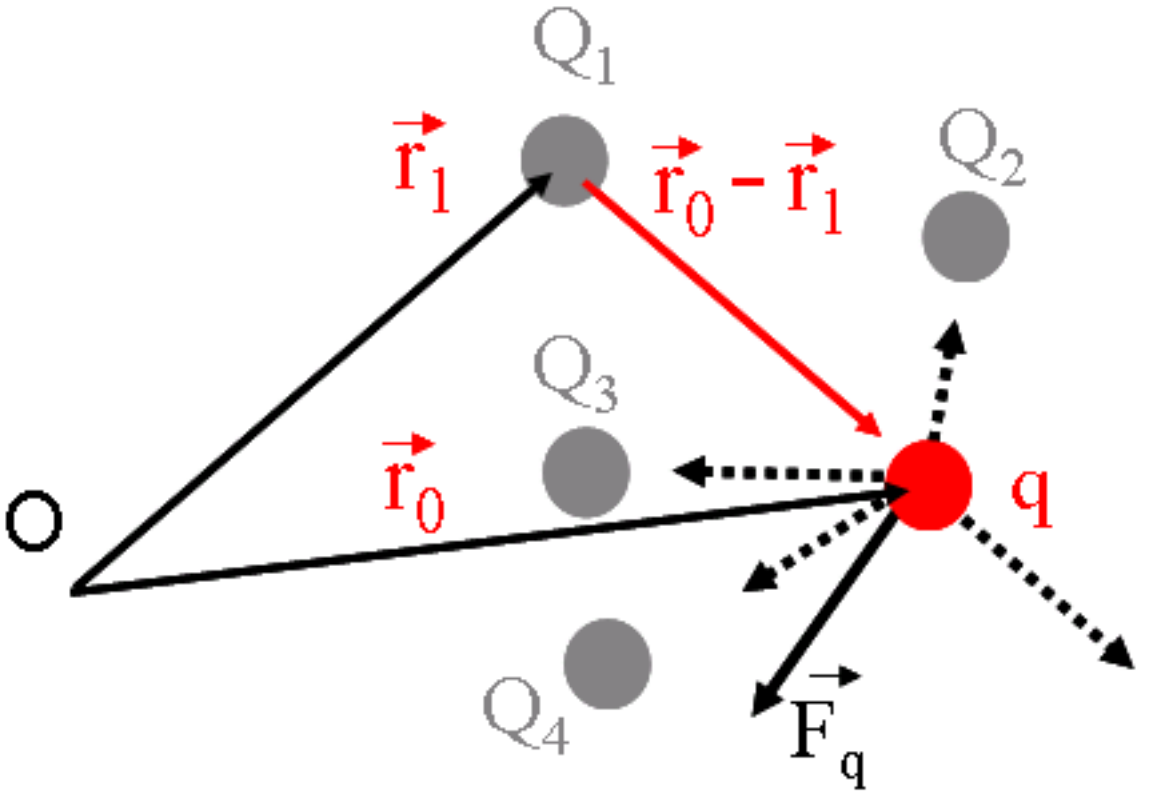
Q_1
$\vec{r}_1$
$\vec{r}_0 - \vec{r}_1$
Q_2
Q_3
$\vec{r}_0$
O
q
Q_4
$\vec{F}_q$